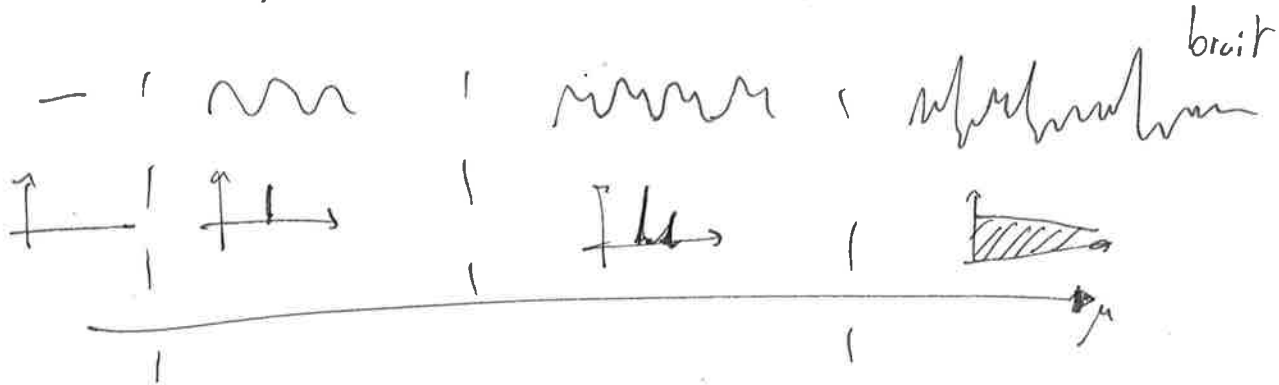


Système : paramètre de contrôle

(I)

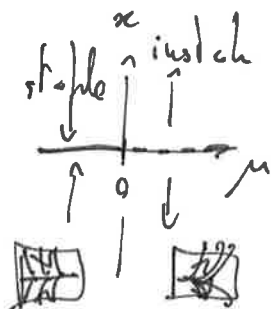
→ augmente: "énergie": comportement + complexe + désordonné

$$\dot{\vec{x}} = f(\vec{x}) \quad \vec{x} \text{ état sys. dyn.}$$

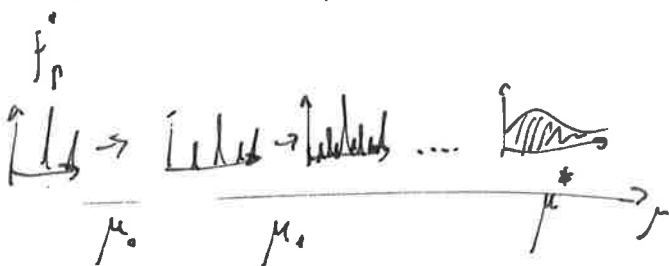


bifurcations: change / qualitatif de comportement
& brutal?
discontinu?

ex: $\dot{x} = \mu x$



exemple: doublement période: un osc. devient 2



Applications

- mécanique (R-B)
- bio φ (cardiaque)
- χ (réact^s oscillants)
- Éca
- optique (laser)
- électronique (diode NL)
- ...

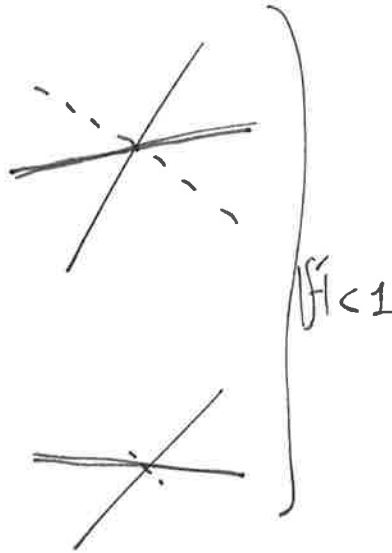
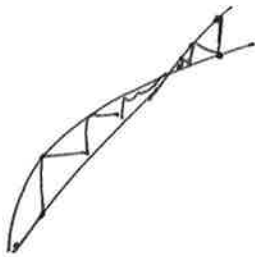
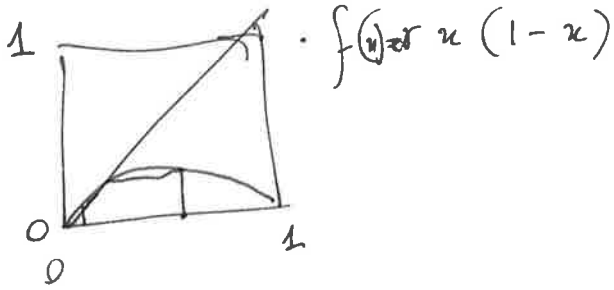
$\text{Re } \mathbb{C}/\mathbb{R} \cong \text{quasiprädig}$

Wm
Wm

Fun fact: quasi-hamiltonian (hpf) $\rightarrow$ $\circ$ $\rightarrow$ $\bigcirc$ $\rightarrow$ $\bigcirc$ $\rightarrow$ $\bigcirc$

Mapping (Reductio ad dimensionality: SD conflict. $\hookrightarrow$ TD conflict.

II



stable



Python

Iterat° d'endomorphismes et groupe
Poincaré de renouement

Charles Coullet & Tresser

1978

Feigenbaum [43, 44] 1978, 79

May & Oster [42] 1980

May 1976

Explorat° diagramme phase

+ définit° α & δ

+ fenêtres périodiques

1 2 4 ... 2^n ...

impair

... 7.53

$\begin{matrix} \uparrow \times 2 \\ \uparrow \times 2 \\ \uparrow \times 2 \end{matrix}$

Li & Yorke [2] 1975

Sharkovskii ordering.

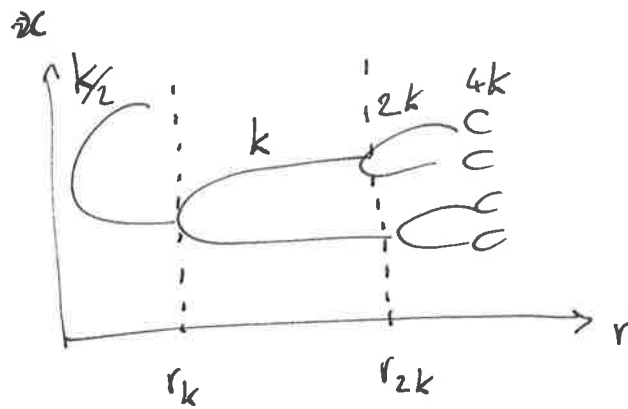
Sharkovskii [38] 1964

Myrberg [37] 1958

Metropolis [40] 1973

$$f_r(x) = r x (1-x)$$

$$f_1^{(k)}(x) = [f_r \circ \dots \circ f_r](x)$$



but : calculer

1. r_k & r_{2k} : $\exists X_k$ tq $f_r^{(k)}(X_k) = X_k$ (stable)

$$g_k = f_r' \Big|_{X_k} = \frac{df}{dx} \Big|_{X_k}$$

$$\triangle ! \quad g_k(r_k) = 1 \text{ (stabilisateur)}$$

$$g_k(r_{2k}) = -1 \text{ (subharmonique)} \quad g_{2k} = 1$$

$$|g_k(r \in]r_k, r_{2k}[)| < 1 \text{ (stable)} \quad g_{2k} = -1$$

but calculer d_k

Si on écrit $g_k(r_k + \delta r) = 1 - q \delta r + \mathcal{O}(\delta r^2)$ NSM

$$g_k(r_{2k}) = -1 = 1 - q \Delta r_k \Rightarrow q \Delta r_k = 2$$

$$g_k(r_{4k}) = g_k^* = 1 - q(\Delta r_k + d_{2k}) = 1 - 2 - q d_{2k}$$

$$\Rightarrow q d_{2k} = -(g_k^* + 1)$$

$$\Rightarrow \delta = \frac{q d_k}{q d_{2k}} = \frac{-2}{1 + g_k^*}$$

* but: from g_k^*

IV.5

$$g_k = \left. \frac{\partial f}{\partial x} \right|_{x=X_k}$$

$$f_r^{(k)}(X_k + \xi) = X_k + g_k \xi + h_k \xi^2 + \dots$$

$\underbrace{h_k = \frac{1}{2} \left. \frac{\partial^2 f}{\partial x^2} \right|_{x=X_k}}$

$$f_r^{(2k)}(X_k + \xi) = f_r^{(k)}(X_k + g_k \xi + h_k \xi^2 + O(\xi^3))$$

$$= X_k + g_k [g_k \xi + h_k \xi^2 + O(\xi^3)] + h_k [g_k \xi + h_k \xi^2 + O(\xi^3)]^2 + O(\xi^3)$$

$$= X_k + (g_k)^2 \xi + \overbrace{g_k h_k [1 + g_k]}^B \xi^2 + \frac{1}{3} C \xi^3 + \dots$$

Par exemple: $\tilde{a} \approx r_{2k}$, $a = g_k \approx -1$ et donc $g_k^2 \approx +1$ et $B \approx 0$

↳ of case!

$$(g_k)^2 = g_{2k} = +1$$

$$X_{2k} = X_k + \xi^* \Rightarrow \xi^* = (g_k)^2 \xi^* + B \xi^{*2} + \frac{1}{3} C \xi^{*3} \Rightarrow \boxed{\frac{1}{3} C \xi^{*2} = 1 - (g_k)^2 - B \xi^*}$$

$$g_{2k} = \cancel{(g_k)^2} + B \xi^* + C \xi^{*2} = 3 - 2(g_k)^2 - \underbrace{2B \xi^*}_{\text{we neglect because } \xi^* \ll 1}$$

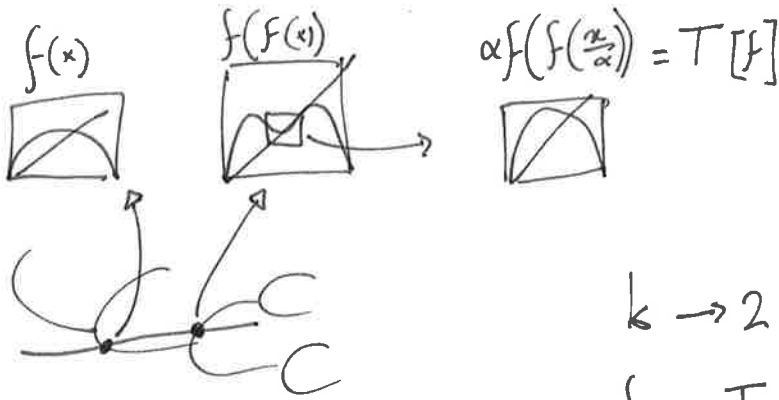
$$\text{and at } r_{2k}: g_{2k} = -1 \Rightarrow (g_k)^2 = 2 \Rightarrow \boxed{g_k^* = \sqrt{2}} \quad (< 0)$$

$$\Rightarrow \delta = \frac{-2}{1 - \sqrt{2}} = 2(1 + \sqrt{2}) \quad \checkmark$$

$\approx 4.828 \quad 3\%$

Renormaliser à la main

$\mathbb{R}^d$



$$k \rightarrow 2k$$

$$f \rightarrow T[f]$$

à la fin on arrive à $g(x)$ tq. $g = Tg$

$$f(x) = 1 - cx^2$$

$$Tf(x) = \alpha \left[1 - c \left(1 - c \left(\frac{x}{\alpha} \right)^2 \right)^2 \right]$$

$$= \cancel{(1-c)} \alpha + \frac{2c^2}{\alpha} x^2 - \frac{c^3}{\alpha^3} x^4 \Rightarrow \alpha = \frac{1}{1-c}$$

2 approaches : $Tf \approx f(x)$

$$Tf(1) \approx f(1)$$

$$\bar{c} = \underbrace{-2c^2(1-c)}_{R(c)}$$

$$c_\infty = \frac{1 \pm \sqrt{3}}{2} \approx 1.366$$

($c_\infty > 1$ because $\alpha < 0$)

$$\bar{c} = -2c^2(1-c) + c^3(1-c)^3$$

$$\alpha_\infty = -1 - \sqrt{3} \approx -2.732 \quad \left| \quad \begin{array}{l} c_\infty \approx 1.402 \\ \alpha_\infty = -2.48 \end{array} \right.$$

$$\alpha = 2.503$$

$$\delta = 4.669$$

$$c_k = R(c_k) \quad R(c) = -2c^2(1-c) \quad \left(R(c) = -2c^2(1-c) + c^3(1-c)^3 \right) \quad \textcircled{V6}$$

évalué du paramètre : on cherche $\delta = \lim_{k \rightarrow \infty} \frac{c_{k+1} - c_k}{c_k - c_{k-1}}$

$$= \lim_{k \rightarrow \infty} \frac{c_{k+1} - c_{\infty} - [c_k - c_{\infty}]}{c_k - c_{\infty} - [c_{k-1} - c_{\infty}]}$$

$$c_{k+1} = R(c_k) = R(c_{\infty} + (c_k - c_{\infty})) - c_{\infty} \quad \text{small}$$

$$= R'(c_{\infty}) [c_k - c_{\infty}]$$

$$= \lim_{k \rightarrow \infty} \frac{[R'(c_{\infty}) - 1] [c_k - c_{\infty}]}{[R'(c_{\infty}) - 1] [c_{k-1} - c_{\infty}]}$$

$$= R'(c_{\infty})$$

$$c_{k+1} = R(c_k)$$

$$= R(c_{\infty} + \frac{c_k - c_{\infty}}{\delta})$$

$$= \underbrace{R(c_{\infty})}_{c_{\infty}} + R'(c_{\infty}) [c_k - c_{\infty}]$$

$$\frac{c_{k+1} - c_{\infty}}{c_k - c_{\infty}} = R'(c_{\infty})$$

$$\delta = \lim_{k \rightarrow \infty} \frac{c_{k+1} - c_k}{c_k - c_{k-1}} = \frac{c_{k+1} - c_{\infty} - (c_k - c_{\infty})}{c_k - c_{\infty} - (c_{k-1} - c_{\infty})} = \frac{(R' - 1)(c_k - c_{\infty})}{(R' - 1)(c_{k-1} - c_{\infty})} = R'(c_{\infty})$$

$$R' = -4c + 6c^2$$

$$| R' = -4c + 6c^2 + 3c^2(1-c)^2 [1-c]$$

$$\delta = 4 + \sqrt{3}$$

$$\delta \simeq 4.467$$

$$\simeq 3.732$$

$$4\%$$

$$22\%$$